1	Structural signatures of igneous sheet intrusion propagation
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3	Craig Magee ^{a*} , James Muirhead ^b , Nick Schofield ^c , Richard J. Walker ^d , Olivier Galland ^e ,
4	Simon Holford ^f , Juan Spacapan ^g , Christopher A-L Jackson ^a , William McCarthy ^h
5	
6	^a Basins Research Group, Department of Earth Science and Engineering, Imperial College
7	London, London, SW7 2BP, UK
8	^b Department of Geological Sciences, University of Idaho, Moscow, Idaho, 83844, USA
9	^c Geology & Petroleum Geology, School of Geosciences, University of Aberdeen, Aberdeen,
10	AB24 3UE, UK
11	^d School of Geography, Geology, and the Environment, University of Leicester, Leicester,
12	LE1 7RH, UK
13	^e Physics of Geological Processes (PGP), The Njord Centre, Department of Geosciences,
14	University of Oslo, Blindern, 0316 Oslo, Postbox 1048, Norway
15	^f Australian School of Petroleum, University of Adelaide, Adelaide, SA 5005, Australia
16	^g Universidad Nacional de La Plata-CONICET-Fundación YPF, 1900 La Plata, Argentina
17	^h Department of Earth Sciences, University of St Andrews, St Andrews, KY16 9AL, UK
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19	*corresponding author: <u>c.magee@imperial.ac.uk</u> (+44 (0)20 7594 6510)
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23	Abstract
24	The geometry and distribution of planar igneous bodies (i.e. sheet intrusions), such as dykes,
25	sills, and inclined sheets, has long been used to determine emplacement mechanics, define
26	melt source locations, and reconstruct palaeostress conditions to shed light on various

tectonic and magmatic processes. Since the 1970's we have recognised that sheet intrusions 27 do not necessarily display a continuous, planar geometry, but commonly consist of segments. 28 29 The morphology of these segments and their connectors is controlled by, and provide insights 30 into, the behaviour of the host rock during emplacement. For example, tensile brittle fracturing leads to the formation of intrusive steps or bridge structures between adjacent 31 segments. In contrast, brittle shear faulting, cataclastic and ductile flow processes, as well as 32 33 heat-induced viscous flow or fluidization, promotes magma finger development. Textural indicators of magma flow (e.g., rock fabrics) reveal that segments are aligned parallel to the 34 35 initial sheet propagation direction. Recognising and mapping segment long axes thus allows melt source location hypotheses, derived from sheet distribution and orientation, to be 36 robustly tested. Despite the information that can be obtained from these structural signatures 37 38 of sheet intrusion propagation, they are largely overlooked by the structural and 39 volcanological communities. To highlight their utility, we briefly review the formation of sheet intrusion segments, discuss how they inform interpretations of magma emplacement, 40 41 and outline future research directions.

42

43 **1. Introduction**

Igneous sheet intrusions are broadly planar bodies (e.g., dykes, sills, and inclined sheets) that 44 facilitate magma flow through Earth's crust. The distribution and geometry of sheet 45 46 intrusions is considered to be broadly controlled by the principal stress axes during emplacement, with intrusion walls typically orienting orthogonal to σ_3 within the σ_1 - σ_2 plane, 47 thus providing a record of syn-emplacement stress conditions (e.g., Anderson, 1936; 48 49 Anderson, 1951; Gautneb and Gudmundsson, 1992; Rubin, 1995; Muirhead et al., 2015). Mapping and analysing the emplacement of igneous sheet swarms therefore allows volcano-50 tectonic processes to be unravelled, as well as aiding in identifying magma source locations 51

and palaeogeographic reconstruction (e.g., Anderson, 1936; Walker, 1993; Ernst et al., 1995;
Geshi, 2005). Overall, the link between intrusion geometry and contemporaneous stress field
conditions has underpinned and dominated research and teaching of igneous sheet
emplacement in the fields of structural geology and volcanology.

Over the last 50 years, it has been recognised that most igneous sheet intrusions 56 consist of segments (e.g., Pollard et al., 1975; Delaney and Pollard, 1981; Rickwood, 1990; 57 58 Schofield et al., 2012a), similar to structures observed in clastic intrusions (e.g., Vétel and Cartwright, 2010) and mineralized veins (e.g., Nicholson and Pollard, 1985). Most research 59 60 has focused on segmented dykes emplaced via tensile elastic fracturing of the host rock (e.g., Delaney and Pollard, 1981; Rickwood, 1990). However, several studies have demonstrated 61 that mechanisms other than tensile elastic fracturing, such as brittle shear faulting, ductile 62 63 flow, and granular flow host rock deformation (e.g., fluidization), can also promote segmentation of sheet intrusions (e.g., Pollard et al., 1975; Hutton, 2009; Schofield et al., 64 2010; Spacapan et al., 2017). Segmentation of igneous sheets is documented over at least five 65 66 orders of magnitude in scale, from intrusions that are a few centimetres to hundreds of meters thick, suggesting that segment formation and linkage are scale independent (Schofield et al., 67 2012a). Variable morphologies of segments (e.g., magma fingers; Pollard et al., 1975; 68 Schofield et al., 2010), as well as those of potential connectors between segments (e.g., 69 intrusive steps, broken bridges; Rickwood, 1990), characterise the broader sheet geometry 70 71 and reflect the mechanical processes that facilitate emplacement (Schofield et al., 2012a). Rock fabric analyses of primary magma flow structures (e.g., chilled margin magnetic 72 fabrics) have shown that the long axes of segments and their connectors are typically parallel 73 74 to the direction of initial sheet propagation (e.g., Baer and Reches, 1987; Rickwood, 1990; Baer, 1995; Liss et al., 2002; Magee et al., 2012; Hoyer and Watkeys, 2017). Identification 75 and analysis of segments and connectors in the field and in seismic reflection data thus 76

provides a simple way to map primary magma propagation patterns and determine synemplacement host rock behaviour (e.g., Rickwood, 1990; Hansen et al., 2004; Thomson and
Hutton, 2004; Trude et al., 2004; Schofield et al., 2012a; Schofield et al., 2012b). Here, our
aim is to: (i) summarise our current understanding of magma segment formation and sheet
intrusion; (ii) highlight how these structures can be used to unravel controls on magma flow
through sheet intrusions in Earth's crust; and (iii) outline future research directions and
implications for the study of sheet intrusion emplacement.

- 84
- 85 2. Primary magma flow indicators
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87 2.1. Intrusive steps and bridge structures formed by tensile brittle fracturing

88 Regardless of their orientation or propagation direction, many sheet intrusions exhibit a stepped geometry consisting of sub-parallel segments that are slightly offset from one another 89 and may overlap (Figs 1-3) (e.g., Delaney and Pollard, 1981; Rickwood, 1990; Schofield et 90 91 al., 2012a). It is broadly accepted that stepped intrusion geometries result from segmentation of a propagating tensile elastic fracture, i.e. oriented orthogonal to σ_3 , immediately ahead of 92 an advancing sheet intrusion (e.g., Delaney and Pollard, 1981; Baer, 1995). As magma fills 93 the fracture, segments begin to inflate and widen through lateral tip propagation, promoting 94 tensile fracture of the intervening host rock and eventual segment coalescence (Fig. 1A) (e.g., 95 96 Rickwood, 1990; Hutton, 2009; Schofield et al., 2012a). Structural signatures of this segmentation are controlled by segment offset, which describes the strike-perpendicular 97 distance between the planes of two segments, and overlap, which can be negative (i.e. 98 99 underlap) and describes the strike-parallel distance between segment tips (Fig. 1A) (cf. Delaney and Pollard, 1981; Rickwood, 1990). We also introduce 'stepping direction', which 100

101 can either be consistent or inconsistent, to define the relative offset direction of adjacent102 segments (Fig. 1B).

103

104 Insert Figure 1

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When viewed in a 2D cross-section (e.g., an outcrop), segments typically appear 106 107 unconnected at their distal end, away from the magma source, whereas increased magma supply in proximal locations promotes their inflation and coalescence to form a continuous 108 109 sheet intrusion (Fig. 1A) (Rickwood, 1990; Schofield et al., 2012a; Schofield et al., 2012b). Connectors between segments are classified as intrusive steps, if the segment overlap is 110 neutral or negative, or bridge structures when segments overlap (Figs 1-3). Changes in 111 112 overlap along segment long axes may mean steps transition into bridge structures and vice versa (Schofield et al., 2012a; Schofield et al., 2012b). Variations in the degree and style of 113 segment connectivity with distance from the magma source imply that the segmentation 114 process results from initial sheet propagation dynamics (Schofield et al., 2012a). 115 116 Insert Figures 2 and 3 117 118 2.1.1. Fracture segmentation 119 120 Two processes are commonly invoked to explain the development of initially unconnected

121 fracture segments: (i) syn-emplacement rotation of the principal stress axes orientations (e.g.,

Pollard et al., 1982; Nicholson and Pollard, 1985; Takada, 1990); and (ii) exploitation of

preferentially oriented, pre-existing structures (e.g., Hutton, 2009; Schofield et al., 2012a;

124 Stephens et al., 2017). Geological systems likely display a combination of these segmentation

mechanisms, and potentially others, so it is therefore important to understand thecharacteristics of each process to decipher their relative contributions.

In the first scenario, a change in the principal stress axes orientation ahead of a 127 propagating fracture, likely due to the onset of mixed mode loading (mode I+II or mode 128 I+III), causes it to twist and split into en-echelon segments that strike orthogonal to the 129 locally reoriented σ₃ axis (Fig. 4A) (Pollard et al., 1982; Nicholson and Pollard, 1985; Cooke 130 131 et al., 1999). This segmentation of mixed mode fractures is dictated by the maximum circumferential stress direction, direction of maximum energy release, maximum principal 132 133 stress, direction of strain energy minimum, and the symmetry criterion (Cooke et al., 1999). The plane broadly defined by the overall geometry of the en-echelon segments remains 134 parallel to the orientation of the original fracture (Fig 4A) (Rickwood, 1990). Steps and 135 136 bridge structures generated due to this style of segmentation have a consistent stepping direction (e.g., Fig. 1B). 137

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139 Insert Figure 4

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The second mechanism for step and bridge formation involves exploitation of 141 preferentially oriented (i.e. with respect to the contemporaneous principal stress axes), pre-142 existing structures by propagating fractures/intrusions (e.g., Hutton, 2009; Schofield et al., 143 144 2012a; Stephens et al., 2017). For example, many sills emplaced into sedimentary strata can be divided into segments that exploited different bedding planes in an attempt to find the least 145 resistant pathway (e.g., Figs 2D and 3A) (Hutton, 2009). Bedding planes are particularly 146 147 exploited because they: (i) exhibit relatively lower tensile strength and fracture toughness compared to intact rock (e.g., Schofield et al., 2012a; Kavanagh and Pavier, 2014; Kavanagh 148 et al., 2017); and/or (ii) mark a significant mechanical contrast in intact rock properties (e.g., 149

150 Poisson's ratio, Young's modulus) that localises strain (e.g., Kavanagh et al., 2006;

Gudmundsson, 2011). In contrast to en-echelon segments, the stepping direction of intrusions
exploiting different pre-existing weaknesses may be inconsistent (Figs 1B and 3E) (Schofield
et al., 2012a).

Alternative mechanisms that may account for segmentation and step formation 154 involve: (i) development of high stress intensities at the leading edge of an intruding sheet, 155 156 promoting rapid crack propagation and formation of a fracture morphology, with a consistent stepping direction, akin to hackle marks (Fig. 4B) (Schofield et al., 2012a); or (ii) the 157 158 occurrence of low or zero fracture toughness, pre-existing structures (e.g., faults), striking orthogonal to the sheet propagation direction, which can promote segmentation and provide a 159 pathway for magma to form a fault-parallel step (Magee et al., 2013; Stephens et al., 2017). 160 161 The stepping direction of sills influenced by pre-existing faults is controlled by the fault dip direction relative to the sheet propagation direction (Magee et al., 2013). In these scenarios, 162 the stepped fracture plane is continuous and thus allows the magma to propagate as a single 163 sheet; bridge structures cannot form via these processes because segments do not overlap 164 (e.g., Fig. 1B). 165

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167 2.1.2. Host rock deformation and bridge development

168 When segments overlap, their inflation may be accommodated by bending of the intervening

host rock bridge (Figs 1A, 3A, and B) (Farmin, 1941; Nicholson and Pollard, 1985;

170 Rickwood, 1990; Hutton, 2009). The monoformal folding of the host rock bridge records a

tangential longitudinal strain relative to the orientation of the folded layers and induces outer-

- arc extension and inner-arc compression along the fold convex and concave surfaces,
- 173 respectively (Hutton, 2009; Schofield et al., 2012a). As magma inflation continues, outer-arc
- 174 extension increases and may exceed the tensile strength of the intact host rock, promoting

development of extension fractures across the bridge (Figs 3B and C) (e.g., Hutton, 2009;

Schofield et al., 2012b). Fractures cross-cutting unfolded bridge structures may also form if
local crack-inducing stresses at segment tips are sufficiently high to promote fracture rotation
and propagation towards each other (e.g., Fig. 3D) (e.g., Olson and Pollard, 1989). Continued
fracture growth and infilling by magma can separate the bridge from one or both sides to
form a broken bridge (Fig. 3B) or a bridge xenolith (Fig. 3D), respectively (Hutton, 2009).

182 2.2. Magma finger formation through brittle and/or non-brittle processes

183 In contrast to established tensile brittle fracturing models, several studies have demonstrated

that magma may intrude via brittle faulting, cataclastic flow, or non-brittle processes (e.g.,

185 Pollard et al., 1975; Duffield et al., 1986; Schofield et al., 2010; Schofield et al., 2012a;

186 Wilson et al., 2016). Such host rock deformation modes lead to the emplacement of magma

187 fingers; i.e. long, linear or sinuous, narrow segments that have blunt and/or bulbous

terminations (e.g., Pollard et al., 1975; Schofield et al., 2010; Schofield et al., 2012a;

189 Spacapan et al., 2017).

Sheet intrusion into unconsolidated or highly incompetent host rocks, where little 190 cohesion between grains and/or low shear moduli inhibits tensile brittle failure, can instigate 191 magma finger formation (e.g., Pollard et al., 1975; Schofield et al. 2012a). For example, 192 accommodation of magma by pore collapse and cataclastic flow can affect sheet intrusions 193 194 emplaced: (i) at shallow-levels in sedimentary basins where host rock sequences have undergone little burial and/or diagenesis (e.g., Einsele et al., 1980; Morgan et al., 2008; 195 Schofield et al., 2012a); or (ii) in strata that have been prevented from undergoing normal 196 197 compaction with burial (Eide et al., 2017). Observed pegmatite bead-strings, which appear similar to magma fingers, formed during syn- or post-metamorphism and emplaced into hot, 198

incompetent rocks suggests high ambient host rock temperatures can promote ductile hostrock deformation and magma finger formation (cf. Bons et al., 2004).

201 Shear failure of unconsolidated and relatively soft (e.g., shale) host rock by brittle faulting and/or ductile deformation can also form and accommodate magma fingers (Fig. 5) 202 (e.g., Pollard, 1973; Duffield et al., 1986; Rubin, 1993; Spacapan et al., 2017). For example, 203 kinematic indicators of such compressional shear structures adjacent to magma fingers in the 204 205 Neuquen Basin, Argentina, indicate that the intrusion 'pushed' into the host rock, leading to confined rock wedging (Fig. 5) (Pollard, 1973; Rubin, 1993; Spacapan et al., 2017). This 206 207 hybrid propagation mechanism, called viscous indentation, is assumed to occur when the viscous shear stresses within a flowing magma, near its intrusion tip, are transferred to and 208 promote shear failure of the host rock (Galland et al., 2014). Viscous indentation is therefore 209 210 expected to primarily accommodate emplacement of viscous magma (Donnadieu and Merle, 1998; Merle and Donnadieu, 2000). 211

212

213 Insert Figure 5

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Intrusion-induced heating (i.e. primary non-brittle emplacement) can cause some host 215 rocks, particularly evaporites and bituminous coals, to behave as high viscosity fluids (i.e. 216 fluidisation), the viscous deformation of which allows low viscosity melt injections to form 217 218 magma fingers (e.g., Fig. 6) (Schofield et al., 2010; Schofield et al., 2012a; Schofield et al., 2014). Magma fingers can also form by fluidization (i.e. granular flow) of coherent, 219 mechanically competent host rock (e.g., Pollard et al., 1975; Schofield et al. 2012a); i.e. 220 221 secondary induced non-brittle magma emplacement (Schofield et al., 2012a). Two secondary induced non-brittle emplacement scenarios may be considered whereby magma intrusion can: 222 (i) promote *in situ* boiling and volatisation of pore-fluids via heating (i.e. thermal 223

fluidization); or (ii) open fractures that rapidly depressurize pore-fluids, which expand and catastrophically disaggregate the host rock (Schofield et al., 2010; Schofield et al., 2012a).

226

227 Insert Figure 6

228

229 **3. Discussion**

Having described how segmentation occurs and is structurally accommodated, here we
discuss selected examples of how this knowledge has been applied and highlight possible
future directions.

233

234 *3.1. Lateral magma flow in mafic sill-complexes*

235 The current paradigm describing crustal magma transport broadly involves the vertical ascent and/or lateral intrusion of dykes (e.g., Gudmundsson, 2006; Cashman and Sparks, 2013). 236 However, recent field- and seismic-based studies that infer magma flow patterns from 237 segment long axes and/or rock fabric analyses within interconnected networks of mafic sills 238 and inclined sheets (i.e. sill-complexes), demonstrate that these systems can facilitate 239 significant vertical (up to 12 km) and lateral (up to 4000 km) magma transport (e.g., 240 Cartwright and Hansen, 2006; Leat, 2008; Muirhead et al., 2014; Magee et al., 2016). The 241 lateral growth of such sill-complexes has been shown to control vent migrations and, 242 243 potentially, transitions from effusive to explosive volcanism in active and extinct mafic monogenetic volcanic fields (e.g., Kavanagh et al., 2015; Muirhead et al., 2016). Mapping 244 segment long axes suggests that sill-complexes may be as important as dykes in various 245 246 tectonic, magmatic, and volcanic processes (Magee et al., 2016).

247

248 3.2. Intrusion opening vectors

Over a century of research has led to the prescribed dogma that sheet opening exclusively 249 involves tensile dilation of Mode I fractures (e.g., Anderson, 1936). Intrusion planes are 250 therefore expected to orient orthogonal to σ_3 , which is a function of the interplay between far-251 252 field and local stress fields (e.g., Anderson, 1936; Anderson, 1951; Odé, 1957; Gautneb and Gudmundsson, 1992; Geshi, 2005). However, from analysing sheet segmentation processes, 253 it is clear that several brittle and non-brittle processes can accommodate the emplacement of 254 255 sheet intrusions that may not orient orthogonal to σ_3 (e.g., Schofield et al., 2012a; Schofield et al., 2014). Although often overlooked, it is therefore important to test the validity of the 256 257 assumed relationship between the orientation of intrusive sheets and σ_3 , through analysis of intrusion opening vectors (e.g., Walker, 1993; Jolly and Sanderson, 1997; Walker, 2016; 258 Walker et al., 2017). Importantly, the geometry of segment connectors provides a record of 259 260 local intrusion opening vectors (e.g., Olson and Pollard, 1989; Walker, 1993; Jolly and Sanderson, 1995; Cooke and Pollard, 1996; Stephens et al., 2017; Stephens et al., 2018). 261 Steps formed during pure tensile opening of parallel magma segments should have virtually 262 zero thickness and simply accommodate shear displacement on a plane orthogonal to the 263 sheet intrusion plane (e.g., Figs 2A and C) (e.g., Stephens et al., 2017). Conversely, thick 264 steps require an opening vector that was *not* orthogonal to the intrusion plane (e.g., Fig. 2D) 265 (Walker et al., 2017). Whilst opening vectors of individual connectors may largely reflect 266 local stress fields related to crack-tip processes (e.g., Olson and Pollard, 1989), identifying 267 268 and collating such opening vector measurements across a sheet intrusion swarm can provide a more robust test of the syn-emplacement stress conditions than analyses of sheet orientation 269 alone (Jolly and Sanderson, 1997; Walker et al., 2017). In particular, cataloguing opening 270 271 vectors of segments within a sheet intrusion complex may help determine whether variablyoriented intrusions can be prescribed to single or multiple stress states. For example, although 272 sill segments within the San Rafael Sub-Volcanic Field, USA range in dip from ~50° SE to 273

~40° NW, all record vertical opening vectors that indicate emplacement of the entire complex
occurred within a single stress state (Stephens et al., 2018).

276

277 3.3. Bridge structures and relay zones

As with intrusions, faults and fractures grow through stages of nucleation and linkage of 278 multiple discontinuous segments (e.g., Cartwright et al., 1996; Walsh et al., 2003). The 279 amount of overlap and offset of fault or fracture segments, and the existence of pre-existing 280 structure, leads to different styles of deformation in the intervening relay zone that 281 282 accommodates displacement gradients between fault segments (e.g., Tentler and Acocella, 2010). Despite the apparent similarity of relay zones and bridge structures (Schofield et al., 283 2012b), few comparisons exist between the resulting ancillary structures associated with 284 285 segmented faults and segmented intrusions. Whilst relay zones have received considerable attention in the literature (e.g., Peacock and Sanderson, 1991; Long and Imber, 2011), to our 286 knowledge there is no catalogue of overlap, offset, and strain parameters for bridge 287 structures. We suggest that systematic study of bridge structures, and comparison to relay 288 zones, could yield important constraints on shared processes. 289

290

291 **4. Conclusion**

Igneous sheet intrusions are not necessarily emplaced as continuous, planar bodies but
commonly develop through the coalescence of discrete magma segments. Segmentation can
be primarily attributed to either: (i) splitting of a tensile brittle fracture propagating ahead of a
sheet intrusion due to stress field rotations or exploitation of pre-existing weaknesses; (ii)
brittle shear and flow (i.e. pore collapse) deformation of poorly consolidated host rocks;
and/or (iii) non-brittle host rock fluidization. By briefly reviewing advances in our
understanding of sheet intrusion growth, we demonstrate how different emplacement

processes produce a variety of segment morphologies (e.g., magma fingers) and connecting structures (e.g., steps and bridge structures), the long axes of which record the initial fracture/magma propagation dynamics. We highlight how mapping of sheet segments and analysing their formation can provide important clues regarding the distribution of melt sources, how magma transits Earth's crust, mechanics of intrusion-induced host rock deformations, and palaeostress states in various volcanic-tectonic environments.

305

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310

311 6. Figure Captions

Figure 1: (A) Schematic diagram documenting the description and development of segments
connected by steps and bridge structures (modified from Magee et al., 2016). Note the
monoformal folding of bridge structures. (B) Schematic diagram defining consistent and
inconsistent stepping directions.

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Figure 2: Steps developed in mafic sheets intruding: (A and B) Mesozoic limestone and shale
metasedimentary rocks on Ardnamurchan, NW Scotland; (C) Neoproterozoic schists at
Mallaig, NW Scotland; and (D) a sedimentary succession on Axel Heiburg island, Canada
(photo courtesy of Martin Jackson).

322 Figure 3: Different bridge structures recorded in mafic intrusions into: (A) Beacon

323 Supergroup sedimentary strata along the Theron Mountains, Antarctica (modified from

324	Hutton, 2009); (B) Beacon Supergroup sedimentary strata along the Allan Hills, Antarctica;
325	(C) a massive dolerite intrusion on Ardnamurchan, NW Scotland; and (D) Mesozoic
326	limestone and shale metasedimentary rocks on Ardnamurchan, NW Scotland. (E) Opacity
327	render of a sill in the Flett Basin, NE Atlantic and corresponding seismic sections detailing
328	intrusive step and bridge growth along i-iv segment boundaries (modified from Schofield et
329	al., 2012b); note that it can be difficult to determine where segments are bounded by steps or
330	bridge structures in seismic reflection data.
331	
332	Figure 4: (A) Schematic showing how a change in the principal stress axes can segment a
333	propagating sheet (after Hutton, 2009). (B) Hackle marks developed on a joint plane
334	(redrawn from Kulander et al., 1979).
335	
336	Figure 5: Small-scale imbricate fold and thrust duplex developed due to viscous indentation
337	of finger-like sill intrusions in the Neuquén Basin, Argentina (modified from Spacapan et al.,
337 338	of finger-like sill intrusions in the Neuquén Basin, Argentina (modified from Spacapan et al., 2017).
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338 339	2017).
338 339 340	2017). Figure 6: (A and B) Magma fingers developed in response to intrusion-induced heating and
338 339 340 341	2017). Figure 6: (A and B) Magma fingers developed in response to intrusion-induced heating and plastic deformation of the host rock coals in the Raton Basin, Colorado (modified from
338 339 340 341 342	2017). Figure 6: (A and B) Magma fingers developed in response to intrusion-induced heating and plastic deformation of the host rock coals in the Raton Basin, Colorado (modified from Schofield et al., 2012a). (C) Schematic diagrams showing the simplified 3D morphology of
338 339 340 341 342 343	2017). Figure 6: (A and B) Magma fingers developed in response to intrusion-induced heating and plastic deformation of the host rock coals in the Raton Basin, Colorado (modified from Schofield et al., 2012a). (C) Schematic diagrams showing the simplified 3D morphology of
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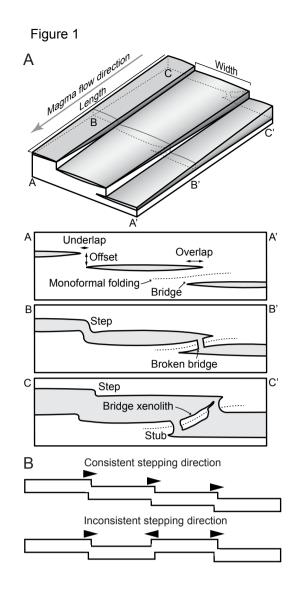


Figure 1: (A) Schematic diagram documenting the description and development of segments connected by steps and bridge structures (redrawn from Magee et al., 2016). (B) Schematic diagram defining consistent and inconsistent stepping directions.

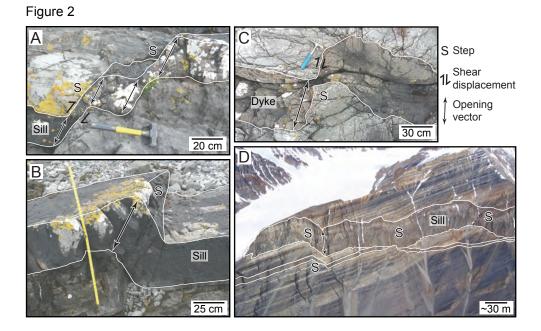


Figure 2: Steps developed in mafic sheets intruding: (A and B) Mesozoic limestone and shale metasedimentary rocks on Ardnamurchan, NW Scotland; (C) Neoproterozoic schists at Mallaig, NW Scotland; and (D) a sedimentary succession on Axel Heiburg island, Canada (photo courtesy of Martin Jackson).

Figure 3

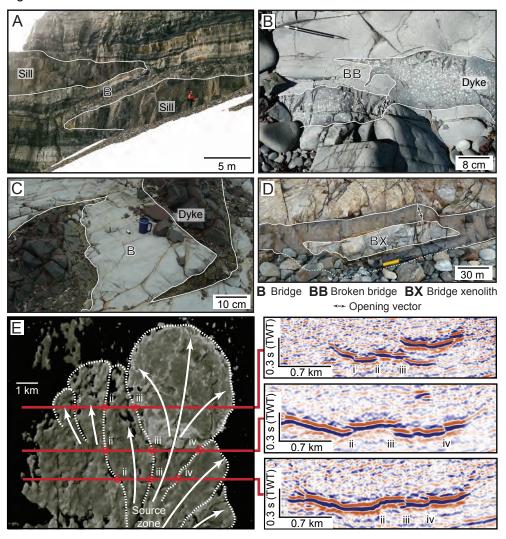


Figure 3: Different bridge structures recorded in mafic intrusions into: (A) Beacon Supergroup sedimentary strata along the Theron Mountains, Antarctica (modified from Hutton, 2009); (B) Beacon Supergroup sedimentary strata along the Allan Hills, Antarctica; (C) a massive dolerite intrusion on Ardnamurchan, NW Scotland; and (D) Mesozoic limestone and shale metasedimentary rocks on Ardnamurchan, NW Scotland. (E) Opacity render of a sill in the Flett Basin, NE Atlantic and corresponding seismic sections detailing intrusive step and bridge growth along i-iv segment boundaries (modified from Schofield et al., 2012b); note that it can be difficult to determine where segments are bounded by steps or bridge structures in seismic reflection data.

Figure 4

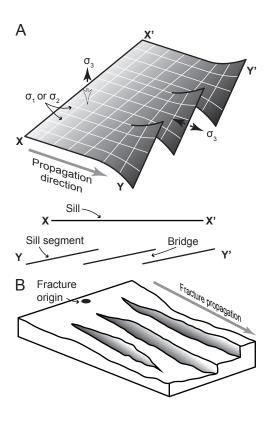


Figure 4: (A) Schematic showing how a change in the principal stress axes can segment a propagating sheet (after Hutton, 2009). (B) Hackle marks developed on a joint plane (redrawn from Kulander et al., 1979).

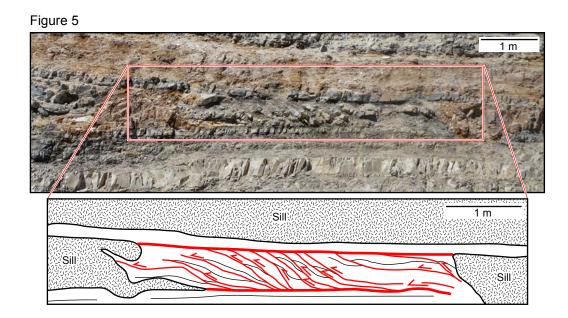


Figure 5: Small-scale imbricate fold and thrust duplex developed due to viscous indentation of finger-like sill intrusions in the Neuquén Basin, Argentina (modified from Spacapan et al., 2017).

Figure 6

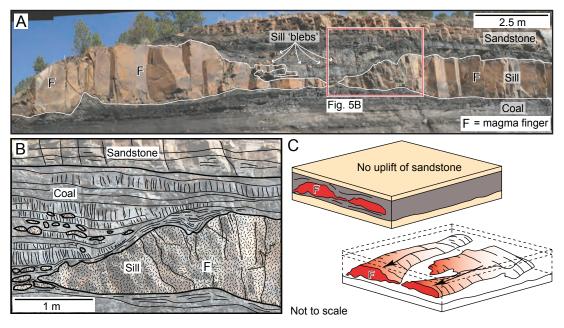


Figure 6: (A and B) Magma fingers developed in response to intrusion-induced heating and plastic deformation of the host rock coals in the Raton Basin, Colorado (modified from Schofield et al., 2012a). (C) Schematic diagrams showing the simplified 3D morphology of the magma fingers in (A and B) (Schofield, 2009).