# Ultra-deep tidal disruption events: prompt self-intersections and observables

Siva Darbha,<sup>1</sup>\* Eric R. Coughlin<sup>®</sup>,<sup>2,3</sup><sup>†</sup> Daniel Kasen<sup>1,2,4</sup> and Chris Nixon<sup>®5</sup>

<sup>1</sup>Department of Physics, University of California, Berkeley, Berkeley, CA 94720, USA

<sup>2</sup>Department of Astronomy and Theoretical Astrophysics Center, University of California, Berkeley, Berkeley, CA 94720, USA

<sup>3</sup>Columbia Astrophysics Laboratory, Columbia University, New York, NY 10027, USA

<sup>4</sup>Nuclear Science Division, Lawrence Berkeley National Laboratory, Berkeley, CA 94720, USA

<sup>5</sup>Department of Physics and Astronomy, University of Leicester, Leicester LE1 7RH, UK

Accepted 2019 July 9. Received 2019 July 9; in original form 2019 February 11

# ABSTRACT

A star approaching a supermassive black hole (SMBH) can be torn apart in a tidal disruption event (TDE). We examine ultra-deep TDEs, a new regime in which the disrupted debris approaches close to the black hole's Schwarzschild radius, and the leading part intersects the trailing part at the first pericentre passage. We calculate the range of penetration factors  $\beta$  versus SMBH masses *M* that produce these prompt self-intersections using a Newtonian analytic estimate and a general relativistic (GR) geodesic model. We find that significant selfintersection of Solar-type stars requires  $\beta \sim 50-127$  for  $M/M_{\odot} = 10^4$ , down to  $\beta \sim 5.6-5.9$  for  $M/M_{\odot} = 10^6$ . We run smoothed particle hydrodynamic (SPH) simulations to corroborate our calculations and find close agreement, with a slightly shallower dependence on *M*. We predict that the shock from the collision emits an X-ray flare lasting  $t \sim 2$  s with  $L \sim 10^{47}$  erg s<sup>-1</sup> at  $E \sim 2$  keV, and the debris has a prompt accretion episode lasting  $t \sim$  several minutes. The events are rare and occur with a rate  $\dot{N} \leq 10^{-7}$  Mpc<sup>-3</sup> yr<sup>-1</sup>. Ultra-deep TDEs can probe the strong gravity and demographics of low-mass SMBHs.

**Key words:** black hole physics – relativistic processes – stars: kinematics and dynamics – galaxies: nuclei – X-rays: bursts.

#### **1 INTRODUCTION**

Stars can be destroyed by the gravitational field of a supermassive black hole (SMBH) if they reach its tidal radius  $r_t \simeq R_*(M/M_*)^{1/3}$ , where the SMBH has mass M and the star has mass  $M_*$  and radius  $R_*$ . Within the tidal radius, the tidal gravity of the SMBH exceeds the self-gravity of the star, and the star is stretched into a stream of debris (Kochanek 1994; Coughlin et al. 2016). This process of stellar destruction by a black hole is known as a tidal disruption event (TDE).

The qualitative timeline of a canonical TDE likely proceeds as follows. If the disrupted star originates near or beyond the sphere of influence of the SMBH, which constitutes the most likely radius from which Solar-like stars are scattered into the loss cone (e.g. Stone & Metzger 2016), then the star's centre of mass (CM) is effectively on a parabolic orbit. At disruption, the stellar debris acquires a range of binding energies due to the tidal potential of the SMBH (Lacy, Townes & Hollenbach 1982),

\* E-mail: siva.darbha@berkeley.edu

† Einstein fellow.

which binds half of the debris to to the black hole and unbinds the other half (Rees 1988). The event is likely 'dark' in this early phase, characterized by the radial expansion of the stream with relatively little emission, though there are some potential signatures (Carter & Luminet 1982; Kobayashi et al. 2004; Guillochon et al. 2009; Kasen & Ramirez-Ruiz 2010; Yalinewich et al. 2019). When the debris returns to pericentre, general relativistic (GR) apsidal precession causes the debris apocentre to deviate from its Keplerian value. This deflection causes the outgoing and incoming material to intersect, dissipate kinetic energy through shocks, and form an accretion disc after several orbits (Cannizzo, Lee & Goodman 1990; Kochanek 1994; Lee, Kang & Ryu 1996; Kim, Park & Lee 1999; Hayasaki, Stone & Loeb 2013, 2016; Guillochon, Manukian & Ramirez-Ruiz 2014; Bonnerot et al. 2016; Shiokawa et al. 2015). When the black hole mass satisfies  $M \lesssim 10^7 M_{\odot}$ , the fallback rate is super-Eddington (for full disruptions of Solar-like stars; Evans & Kochanek 1989; Wu, Coughlin & Nixon 2018), which can lead to the production of radiation driven winds (Strubbe & Quataert 2009) and jets (Coughlin & Begelman 2014). The accretion (and associated outflows) produces a highly luminous, short-lived emission event, in which the lightcurve rapidly rises, reaches a peak, and decays as a power law.

While this timeline is likely upheld for most TDEs, the detailed appearance of a given TDE depends on the properties of the disrupted star, the SMBH, and the specifics of the stellar orbit (e.g. the pericentre). The event horizon of a non-rotating black hole is determined by the Schwarzschild radius,  $r_{\rm S} = 2r_{\rm g}$ , where  $r_{\rm g} = GM/c^2$  is the gravitational radius. The encounter strength can be parametrized by the penetration factor  $\beta = L_t^2/L_{\rm cm}^2$ , where  $L_t^2 = 2GMr_t$  and  $L_{\rm cm}$  is the specific angular momentum of the stellar CM. In Newtonian encounters, the stellar CM angular momentum is  $L_{\rm cm}^2 = 2GMr_{\rm p}$ , where  $r_{\rm p}$  is the CM pericentre distance, and the penetration factor becomes  $\beta = r_t/r_{\rm p}$  (Carter & Luminet 1982). We can also define  $r_{\rm p}$  in this way even for relativistic encounters, though in this case it is simply a parameter and has diminished physical significance; the true GR pericentre  $(r_{\rm p})_{\rm GR}$  will be different here, and will even be undefined if the star is captured by the SMBH.

The general picture of a canonical TDE given above has been confirmed numerically for large tidal radii ( $r_t \gg r_S$ ) and shallow encounters ( $\beta \sim 1$ , with  $r_p \sim r_t$ ). Simulations using smoothed particle hydrodynamics (SPH) and grid-based methods have observed the predicted spread in energies (for early work, see Evans & Kochanek 1989; for more recent work, see Lodato, King & Pringle 2009; Guillochon & Ramirez-Ruiz 2013; Coughlin & Nixon 2015), and the stream–stream collisions leading to debris circularization (Bonnerot et al. 2016; Hayasaki et al. 2016; Jiang, Guillochon & Loeb 2016). Analytic estimates (Lodato & Rossi 2011) and detailed radiative transfer calculations (Strubbe & Murray 2015; Roth et al. 2016; Roth & Kasen 2018) have supported the expected behaviour of the light curve and characterized its spectral features.

However, the situation can change dramatically for large tidal radii  $(r_t \gg r_s)$  when the star undergoes an ultra-deep encounter ( $\beta$  $\gg$  1, with  $(r_p)_{GR} \sim r_S$ ). In this case, the star is tidally stretched for a long duration as it approaches the BH; indeed, when its CM reaches  $(r_{\rm p})_{\rm GR}$ , the star's leading and trailing edges can be displaced much farther apart than the initial stellar radius  $R_*$ . In addition, since the apsidal precession angle  $\Delta \phi \gtrsim 2\pi$  when  $(r_p)_{\rm GR} \sim r_{\rm S}$ , the leading edge of the extremely stretched star can conceivably intersect the trailing edge before the latter reaches its pericentre. In this case, the stream will intersect itself roughly at pericentre, the debris will shock heat and dissipate orbital energy, and some fraction of the star will accrete onto the SMBH almost instantaneously at this first pericentre passage. These extreme TDEs will thus exhibit no delay between disruption and accretion and, consequently, show a very different rise-peak-decay signature. This distinct signature may allow us to probe the tidal deformation of the star near pericentre and the debris dynamics in strong gravity.

There have been efforts to examine the signatures of deep encounters of main-sequence stars on SMBHs (Bicknell & Gingold 1983; Laguna et al. 1993; Brassart & Luminet 2008, 2010; Evans, Laguna & Eracleous 2015; Sądowski et al. 2016; Tejeda et al. 2017), though not in the ultra-deep regime that produces prompt selfintersections. The results still reveal interesting features that may also occur in our case. For instance, Evans et al. (2015) examine disruptions of main-sequence stars in deep encounters ( $\beta = 10, 15$ ) with SMBHs of mass  $M = 10^5 M_{\odot}$ . Their simulations exhibit an early accretion burst followed by a flat accretion rate at later times; strong GR effects modify the  $\dot{M} \sim t^{-5/3}$  late-time accretion rate expected of canonical TDEs.

There has been greater focus on deep encounters of white dwarfs (WDs) on stellar and intermediate-mass BHs (Luminet & Pichon 1989b; Frolov et al. 1994; Rosswog, Ramirez-Ruiz & Hix 2009; Haas et al. 2012; MacLeod et al. 2016; Tanikawa et al. 2017; Kawana, Tanikawa & Yoshida 2018; Anninos et al. 2018), since these are more promising as sites of nuclear ignition near pericentre and as sources for gravitational wave (GW) emission. As in the case of main-sequence stars, much of this work has not directly examined the prompt self-intersection regime. One notable exception is Kawana et al. (2018), who study deep encounters using 3D SPH simulations coupled with a nuclear reaction  $\alpha$ -network, and observe prompt self-intersections at pericentre for encounters with a WD of mass  $M_{\rm WD} = 0.6 M_{\odot}$ , an SMBH of mass  $M = 10 M_{\odot}$ , and penetration factor  $\beta = 5$ . They label these 'Type III TDEs,' and find that these energetic collisions heat the debris and efficiently circularize it, but the heating is not sufficient to ignite nuclear reactions; they note, though, that their simulations likely do not fully resolve the collision numerically.

In this paper, we investigate the possibility of prompt selfintersections from ultra-deep TDEs of main-sequence stars. In Section 2, we outline our parameter regime and present two models to calculate the range of encounter depths for which we expect prompt self-intersections to occur; first, we derive a simple, order-of-magnitude estimate in Newtonian gravity (Section 2.1), and second, we model the geodesics of debris elements in the Schwarzschild metric under the impulse (or 'frozen-in') approximation (Section 2.2). In Section 3, we use SPH simulations to corroborate our estimated range of encounter depths for which prompt self-intersections occur. In Section 4, we conclude and discuss the possible signatures from these extreme TDEs.

# 2 MODELS

We defined the tidal radius  $r_t$ , the penetration factor  $\beta$ , and the Schwarzschild radius  $r_S$  in the Introduction. These parametrize the nature of the encounter. We use the Newtonian expression for  $r_t$ , which differs from the relativistic expression only marginally for the parameters that we examine below (Kesden 2012a; Servin & Kesden 2017). We note that some authors adopt the definition  $\beta = r_t/(r_p)_{GR}$  when studying relativistic TDEs (e.g. Guillochon & Ramirez-Ruiz 2013; Tejeda et al. 2017); this is different from our definition above, so one must exercise care when making comparisons.

We examine TDEs whose parameters satisfy the hierarchy  $R_*$ ,  $r_S \ll r_t$ . The condition  $r_S \ll r_t$  permits deep ( $\beta \gg 1$ ) encounters, and can be expressed as

$$\frac{r_{\rm S}}{r_{\rm t}} \simeq 9.1 \times 10^{-3} M_5^{2/3} m_*^{1/3} r_*^{-1} \ll 1 \tag{1}$$

where  $m_* \equiv M_*/M_{\odot}$ ,  $r_* \equiv R_*/R_{\odot}$ , and  $M_5 \equiv M/(10^5 M_{\odot})$ . The condition  $R_* \ll r_t$  allows us to use first-order expressions for the spread in coordinates, energy, and angular momentum across the star, and can be expressed as

$$\frac{R_*}{r_{\rm t}} \simeq 2.2 \times 10^{-2} M_5^{-1/3} m_*^{1/3} \ll 1 \tag{2}$$

We restrict our attention to ratios  $\lesssim 5 \times 10^{-2}$ . For Solar-type stars, this implies SMBH masses in the range  $M \sim (10^4 - 10^6) M_{\odot}$ . For stars of mass  $M_*/M_{\odot} = 10$  and radius  $R_* = R_{\odot}(M_*/M_{\odot})^{\alpha}$  with  $\alpha = 0.57$ , which holds for main-sequence stars with masses  $M_*/M_{\odot} \gtrsim 1$  (Torres, Andersen & Giménez 2010), this implies SMBH masses in the range  $M \sim (5 \times 10^4 - 5 \times 10^6) M_{\odot}$ .

For highly penetrating encounters ( $\beta \gg 1$ ), the stellar debris experiences strong tidal compression near pericentre, which leads to a rapid pressure increase and the generation of a shock during the bounce phase (Carter & Luminet 1982, 1983; Bicknell & Gingold 1983). Carter & Luminet (1982) used geometrical arguments and the adiabatic approximation to estimate that, for a  $\gamma = 5/3$  polytrope,

the central stellar density  $\rho_*$  and temperature  $T_*$  are compressed to maximum values of  $\rho_m \simeq \beta^3 \rho_*$  and  $T_m \simeq \beta^2 T_*$  near pericentre, and argued that this would ignite nuclear reactions. This process has been explored in subsequent work using detailed hydrodynamic simulations, and there remains uncertainty over the extent of compression, the plausibility of nuclear reactions, and the effects on the debris orbits approaching pericentre (Carter & Luminet 1983; Bicknell & Gingold 1983; Laguna et al. 1993; Kobayashi et al. 2004; Guillochon et al. 2009; Brassart & Luminet 2008, 2010; Stone, Sari & Loeb 2013; Evans et al. 2015; Tejeda et al. 2017). Most recently, Tejeda et al. (2017) ran extensive SPH simulations for TDEs by Kerr BHs and found strong compression in encounters with  $\beta \gtrsim 10$ ; Evans et al. (2015), in contrast, performed GR hydrodynamic simulations, and did not observe strong compression in encounters with  $\beta \sim 10-15$  (for Solar-type stars and  $M = 10^5 M_{\odot}$ SMBHs), and instead found that the star has a large spatial spread before pericentre passage due to tidal stretching in the orbital plane.

In this section, we seek simple estimates for the range of  $\beta$  for which the disrupted debris promptly self-intersects. We thus ignore hydrodynamic effects at pericentre, namely strong compression, shock generation, and nuclear detonation. While these effects could alter the qualitative behaviour of the debris following self-intersection, and thus the appearance of the event, they should not drastically impact the ability of the star to promptly self-intersect in the first place.

# 2.1 Analytic model

In this subsection, we derive an order-of-magnitude expression in Newtonian gravity for the values of  $\beta$  for which we expect the star to undergo self-intersection prior to leaving pericentre.

Prior to reaching pericentre, we can effectively model the stellar CM on a purely radial orbit since its pericentre is very small relative to the tidal radius. For a parabolic orbit, the energy of the CM is  $\epsilon = 0$ . If we take the CM to be at the tidal radius  $r_t$  at time t = 0, then we can write its position as an explicit function of time as

$$r_{\rm cm} = r_{\rm t} \left( 1 - \frac{3}{2} \tilde{t} \right)^{2/3},$$
 (3)

where  $\tilde{t} = t/\sqrt{r_t^3/2GM}$ . The CM thus reaches its pericentre  $r_p$  at time

$$\tilde{t}_{\rm p} = \frac{2}{3}(1 - \beta^{-3/2}). \tag{4}$$

The tidal field stretches the star in the radial direction and compresses it in the two orthogonal directions. If *R* is the radial extent of the stretched star, then for  $R \ll r_{\rm cm}$ , the tidal acceleration in the radial direction is

$$\ddot{R} = \left(\frac{r_{\rm t}}{r_{\rm cm}}\right)^3 R = R \left(1 - \frac{3}{2}\tilde{t}\right)^{-2} \tag{5}$$

where the overdot denotes differentiation with respect to  $\tilde{t}$ . With the initial conditions  $R(0) = 2R_*$  (the stellar radius is  $R_*$  at the tidal radius) and  $\dot{R}(0) = 0$  (the star is in hydrostatic equilibrium at the tidal radius) the solution for the radial extent of the star as a function of time is

$$R = R_* \left[ \frac{8}{5} \left( 1 - \frac{3}{2}\tilde{t} \right)^{-1/3} + \frac{2}{5} \left( 1 - \frac{3}{2}\tilde{t} \right)^{4/3} \right].$$
 (6)

By the time the CM reaches  $r_p$ , the condition  $R \ll r_{cm}$  is no longer satisfied; nevertheless, if we apply our result to obtain a rough

estimate, then the star at this point has a radial extent of

$$R_{\rm p} = R_* \left(\frac{8}{5}\beta^{1/2} + \frac{2}{5}\beta^{-2}\right) \simeq \frac{8}{5}R_*\beta^{1/2},\tag{7}$$

where the last line follows from the assumption  $\beta \gg 1$ . We note that the leading order scaling  $R_{\rm p} \sim \beta^{1/2}$  is equal to that found in equation (B6) of Stone et al. (2013) for the long principal axis of a tidally deformed star on a parabolic orbit. The higher order terms differ, though, likely because we evaluate the deformation at different points along the orbit.

As the stretched star passes through pericentre, it will become long enough to intersect itself if  $R_p \ge 2\pi r_p$ ; using the expressions for  $\beta$  and  $r_t$ , this becomes

$$\beta \ge \beta_{\rm c} \simeq \left(\frac{5\pi}{4}\right)^{2/3} \left(\frac{M}{M_*}\right)^{2/9} \simeq 32M_5^{2/9}m_*^{-2/9} \tag{8}$$

which is independent of the stellar radius and only depends weakly on the mass of the SMBH.

Equation (8) does not explicitly incorporate GR effects. In particular, (1) some or all of the star may be captured by the BH, (2) the relative precession angle of uncaptured debris must be  $\Delta \phi > 2\pi$  for a self-intersection to occur, and (3) the GR tidal deformation is stronger (in a static, spherically symmetric space-time) than the Newtonian tidal field at a given radial coordinate (Luminet & Marck 1985; Servin & Kesden 2017). Nevertheless, stars will become stretched appreciably as above only in ultra-deep encounters, for which we also expect large apsidal precession, and thus this expression provides a rough, order-of-magnitude estimate of the  $\beta$  required to achieve a prompt self-intersection.

## 2.2 Geodesic model

In this subsection, we model the disrupted debris on independent Schwarzschild geodesics to estimate the range of encounter depths for which it promptly intersects itself. Here and for the remainder of this paper, we use geometric units G = c = 1 and a metric signature (-, +, +, +). We often express tensors by their symbols alone. We also use early Latin indices  $a, b, \ldots$  to label tensors in abstract index notation, and Greek indices to labels components. In addition, we use Greek indices to refer to spacetime components  $\mu = 0, 1, 2,$  and 3, and middle Latin indices  $i, j, \ldots$  to refer to spatial components i = 1, 2, and 3.

We integrate the geodesics using the Runge–Kutta–Fehlberg 78 integrator from the C+ + BOOST libraries, setting the absolute and relative errors to  $\epsilon_{abs} = 10^{-12}$  and  $\epsilon_{rel} = 10^{-10}$ . This is a high-order adaptive integrator that has been used to accurately model null and time-like geodesics for GR ray tracing in strong gravity (Vincent et al. 2011; Grould, Paumard & Perrin 2016).

The tidal force at large radii (compared to the gravitational radius) varies as  $\sim 1/r^3$ , where *r* is the radial coordinate from the SMBH. The strength of the SMBH's tidal force compared to a star's gravitational self-force thus increases rapidly as the star crosses  $r_t$ , which suggests that the tidal force can be modelled as an impulsive effect that is activated at  $r_t$ . Specifically, for  $r \gtrsim r_t$ , tidal effects are negligible and we can model the star as if it retains perfect hydrostatic balance; for  $r \lesssim r_t$ , tidal effects are dominant and we can model the motion of stellar gas parcels as independent orbits in the gravitational field of the SMBH. The orbital elements (e.g. specific energy and angular momentum) of a given gas parcel are therefore 'frozen-in' once the stellar CM reaches the tidal radius (Lodato et al. 2009).

Recently, Steinberg et al. (2019) showed that the 'frozen-in' approximation does not adequately capture the energy distribution

of the debris, which is modified by self-gravity throughout the encounter, though the gas parcels are still well modelled by individual orbits, a result validated by our simulations (Section 3). In addition, the star likely experiences strong tidal compression and shock generation at pericentre, and thus the 'frozen-in' approximation is not strictly valid at this point. The star also experiences additional tidal deformations prior to reaching the tidal radius (Lodato et al. 2009; Coughlin & Nixon 2015). It is sufficient, though, for our estimates in this subsection to ignore these difficulties. We will address the importance of the latter in Section 3 with the aid of hydrodynamic simulations. The assumption of geodesic orbits should also be particularly well maintained for the equatorial plane of the star, about which the tidal compression is symmetric.

The gravity of a non-spinning and chargeless SMBH of mass M is described by the Schwarzschild metric, which is the general exterior solution for a static, spherically symmetric space-time (Birkhoff & Langer 1923; Hawking & Ellis 1973). The metric g has the associated line element (Chandrasekhar 1983)

$$ds^{2} = -\left(1 - \frac{2M}{r}\right)dt^{2} + \left(1 - \frac{2M}{r}\right)^{-1}dr^{2} + r^{2}d\theta^{2} + r^{2}\sin^{2}\theta d\phi^{2}$$
(9)

where we express it in Schwarzschild coordinates  $x^{\mu} = (x^0, x^1, x^2, x^3) = (t, r, \theta, \phi)$ . A timelike geodesic  $\gamma$  has four velocity  $u = \gamma'(\tau) = \dot{x}^{\mu} \partial_{\mu}$ , where we parametrize the geodesic by the proper time  $\tau$  and where the overdot denotes differentiation with respect to  $\tau$ ,  $\dot{x}^{\mu} \equiv \frac{d(x^{\mu} \circ \gamma)}{d\tau}$ . The four velocity satisfies  $g_{\mu\nu} \dot{x}^{\mu} \dot{x}^{\nu} = -1$ . The spatial motion of a geodesic is restricted to a 2D plane, which we can set equal to the equatorial plane ( $\theta = \pi/2$ ,  $\dot{\theta} = 0$ ) due to spherical symmetry.

The Lagrangian for a free particle in geodesic motion is  $\mathcal{L} = \frac{1}{2}g_{\mu\nu}\dot{x}^{\mu}\dot{x}^{\nu}$ , and the corresponding Hamiltonian is  $\mathcal{H} = p_{\mu}\dot{x}^{\mu} - \mathcal{L} = \frac{1}{2}g^{\mu\nu}p_{\mu}p_{\nu}$ , where  $p_{\mu} = \frac{\partial \mathcal{L}}{\partial\dot{x}^{\mu}}$  are the (covariant) canonical momenta. The equations of motion can be obtained from Hamilton's equations,  $\dot{x}^{\mu} = \frac{\partial \mathcal{H}}{\partial p_{\mu}}$  and  $\dot{p}_{\mu} = -\frac{\partial \mathcal{H}}{\partial x^{\mu}}$ . The Hamiltonian is independent of *t* and  $\phi$ , so  $\dot{p}_{t} = \dot{p}_{\phi} = 0$ , leading to the conserved quantities  $E = -p_{t}$  (the specific energy) and  $L = p_{\phi}$  (the specific angular momentum). The equations of motion can thus be written as

$$\dot{t} = \left(1 - \frac{2M}{r}\right)^{-1} E \tag{10}$$

$$\dot{\phi} = \frac{L}{r^2} \tag{11}$$

$$\dot{r} = \left(1 - \frac{2M}{r}\right) p_{\rm r} \tag{12}$$

$$\dot{p}_{\rm r} = -\frac{M}{r^2} p_{\rm r}^2 - \frac{ME^2}{(r-2M)^2} + \frac{L^2}{r^3}$$
(13)

The radial momentum can be written explicitly as

$$p_{\rm r}^2 = \left(1 - \frac{2M}{r}\right)^{-2} \left[E^2 - 2V(r)\right]$$
(14)

$$V(r) = \frac{1}{2} - \frac{M}{r} + \frac{L^2}{2r^2} - \frac{ML^2}{r^3}$$
(15)

where V(r) is the 1D effective potential.

Let  $\alpha$  be the CM geodesic parametrized by  $\tau$ , with four velocity  $u_{\rm cm} = \alpha'(\tau) = \dot{x}_{\rm cm}^{\mu} \partial_{\mu}$ . The CM has angular momentum  $L_{\rm cm}$ , which must satisfy  $L_{\rm cm} \lesssim 2Mr_{\rm t}$  for a disruption to occur, and energy

 $E_{\rm cm} = 1$ , since the incident unbound stars approach the SMBH on roughly parabolic orbits (though these can change under different physical circumstances; Stone & Loeb 2011; Coughlin et al. 2017; Darbha et al. 2018). The stellar gas parcels around the CM have a range of coordinates, energies, and angular momenta at the moment of disruption. These can be calculated rigorously and self-consistently in terms of Fermi Normal Coordinates (FNCs) defined along  $\alpha$  (Manasse & Misner 1963). We construct the FNCs using the general approach of previous work (Luminet & Marck 1985; Brassart & Luminet 2010; Kesden 2012b), which we briefly summarize.

Let  $\lambda_{(\mu)}$  be an orthonormal tetrad (ONT) defined along  $\alpha$ , where the circular brackets label the tetrad elements. The timelike vector  $\lambda_{(0)}$  is equal to the tangent of  $\alpha$  (i.e. the four velocity) and the tetrad is parallel-propagated along  $\alpha(\tau)$ . All together,

$$g(\lambda_{(\mu)}, \lambda_{(\nu)}) = \eta_{(\mu)(\nu)} \tag{16}$$

$$\lambda_{(0)} = u_{\rm cm} \tag{17}$$

$$\nabla_{\lambda_{(0)}}\lambda_{(\mu)} = 0 \tag{18}$$

where  $\eta$  is the Minkowski metric. The indices in circular brackets are raised and lowered using  $\eta$ , and those not in circular brackets are done so using g (Chandrasekhar 1983; Wald 1984). We use the tetrad given by Luminet & Marck (1985) (corrected in Brassart & Luminet 2010), and present them in Appendix A. We note that these were obtained from the more general expressions calculated by Marck (1983) in the Kerr metric.

Consider a debris element at a point q in the neighbourhood of  $\alpha$ . We take  $\alpha(0) = p_0$  as an arbitrary reference point. There is a unique spacelike geodesic  $\chi$  that passes through q and is orthogonal to  $\alpha$  at some point  $\alpha(\tau) = p$ , where we parametrize  $\chi$  by the proper distance s. We take  $\chi(0) = p$ , so  $\chi(s) = q$  for some s. Let  $X = X^{(i)}\lambda_{(i)}$  be the space-like vector that is tangent to  $\chi$  at p such that the proper distance to q along  $\chi$  is s = ||X||, where  $||X|| = [g(X, X)]^{1/2} = [X^{(i)}X_{(i)}]^{1/2}$ . The FNCs of the debris element at q are defined to be  $(\tau, X^{(i)})$ .

We take the reference point  $p_0$  to be the point at which the CM is at the tidal radius. We note that X is parallel-propagated along  $\alpha$  by construction, and so the stellar gas parcels do not accelerate relative to the CM geodesic before disruption. The gas parcels fall in the range  $||X|| \le R_*$ . For convenience, we define the unscaled vector  $\tilde{X}$ by  $X = R_* \tilde{X}$ , where  $||\tilde{X}|| \le 1$ .

To first order, the debris element with FNCs (0,  $X^{(i)}$ ) has Schwarzschild coordinates  $x^{\mu} = x^{\mu}_{cm} + X^{(i)}\lambda^{\mu}_{(i)}$ , and energy and angular momentum

$$E(X^{(i)}) = E_{\rm cm} + \Delta E(X^{(i)})$$
 (19)

$$L(X^{(i)}) = L_{\rm cm} + \Delta L(X^{(i)})$$
(20)

with deviations given by (Kesden 2012b)

$$\Delta E(X^{(i)}) = \nabla_X E_{\rm cm} = -g_{\mu\nu} \lambda^{\mu}_{(0)} X^{(i)} \lambda^{\beta}_{(i)} \Gamma^{\nu}_{\beta t}$$
(21)

$$\Delta L(X^{(i)}) = \nabla_X L_{\rm cm} = g_{\mu\nu} \lambda^{\mu}_{(0)} X^{(i)} \lambda^{\beta}_{(i)} \Gamma^{\nu}_{\beta\phi}$$
<sup>(22)</sup>

where  $\nabla$  is the Levi–Civita connection and  $\Gamma$  are the Christoffel symbols. We can write these as

$$\Delta E(X^{(i)}) = \frac{M}{r_{\rm cm}^2} \sum_{i=1,3} X^{(i)} \left( \dot{t}_{\rm cm} \lambda_{(i)}^r - \dot{r}_{\rm cm} \lambda_{(i)}^t \right)$$
(23)

$$\Delta L(X^{(i)}) = r_{\rm cm} \sum_{i=1,3} X^{(i)} \left( -\dot{r}_{\rm cm} \lambda^{\phi}_{(i)} + \dot{\phi}_{\rm cm} \lambda^{r}_{(i)} \right)$$
(24)



Figure 1. The debris in the equatorial plane ( $X^{(2)} = 0$ ) for  $M/M_{\odot} = 5 \times 10^4$ , Solar-type stars,  $E_{\rm cm} = 1$ , and  $L_{\rm cm} = 4.1M$ , described in terms of (a) the coordinates ( $\tilde{X}^{(1)}$ ,  $\tilde{X}^{(3)}$ ) and (b) the parameters (E, L). The black dashed line shows the curve separating captured (below) and uncaptured (above) debris elements. The black circle marks the CM. The red (blue) dot shows the geodesic with the smallest (largest) value of L.

We note that these do not depend on  $X^{(2)}$  explicitly, only through the constraint  $||X|| \le R_*$ . We only need the first order expressions due to the parameter regime that we consider (equations 1 and 2), though the extension to a more general regime would require higher order corrections (Ishii, Shibata & Mino 2005; Cheng & Evans 2013; Cheng & Bogdanović 2014).

In our setup, we set the stellar CM to move in the equatorial plane  $(\theta = \pi/2, \dot{\theta} = 0)$  and to be at the tidal radius along the *x*-axis (*r*,  $\theta, \phi) = (r_t, \pi/2, 0)$ . We restrict our attention to the post-disruption debris geodesics also in the equatorial plane  $(X^{(2)} = 0)$ . This is the symmetry plane around which the debris moves. This restriction to equatorial debris reduces the degrees of freedom to the (*t*, *r*,  $\phi$ ) coordinates, which simplifies the condition for self-intersection. The equatorial geodesics are uniquely identified by the coordinates ( $X^{(1)}$ ,  $X^{(3)}$ ), which map in a linear, one-to-one fashion to the parameters (*E*, *L*) for a given  $E_{\rm cm}$ ,  $L_{\rm cm}$ , and  $r_t$ .

The ultimate fate of a debris element with parameters (E, L) can be determined from V(r). If  $L^2 < 12M^2$ , the debris will undoubtedly be captured by the SMBH. If  $L^2 \ge 12M^2$ , the debris will be captured (including stalling indefinitely) if  $V(r_-) \le \frac{E^2}{2}$ , where  $r_-(L) \equiv \frac{L^2}{2M} [1 - (1 - \frac{12M^2}{L^2})^{1/2}]$  is the radius of the unstable circular orbit, and the angular momentum for capture  $L_{\text{cap}}$  is defined from  $V(r_-(L_{\text{cap}})) = \frac{E^2}{2}$ . In particular, geodesics with E = 1 will be captured if  $L^2 \le L_{\text{cap}}^2 = 16M^2$ .

Fig. 1 shows the coordinates and parameters of the equatorial debris, and the regions which are captured and uncaptured, for one set of SMBH and stellar parameters. The geometry of the regions can be understood simply. The debris elements in the equatorial plane have coordinates in the domain  $\|\tilde{X}\|^2 = \tilde{X}^{(i)}\tilde{X}_{(i)} = (\tilde{X}^{(1)})^2 + (\tilde{X}^{(3)})^2 \leq 1$ . The linear map in equations (19)–(24) maps this circle in the  $\tilde{X}^{(1)}\tilde{X}^{(3)}$ -plane to the ellipse  $A(E - E_{cm})^2 + B(E - E_{cm})[(L - L_{cm})/M] + C[(L - L_{cm})/M]^2 \leq 1$  in the *EL*-plane, where *A*, *B*, and *C* each depend on  $E_{cm}$ ,  $L_{cm}$ , and  $r_{cm}$ . Since  $E_{cm} = 1$  and  $\Delta E/E_{cm} \ll 1$ , the curve  $V(r_{-}) = E^2/2$  in the *EL*-plane that separates the captured

and uncaptured debris is roughly a horizontal line at  $L = L_{cap} = 4M$ , and is mapped in inverse to the line shown in the  $\tilde{X}^{(1)}\tilde{X}^{(3)}$ -plane.

The debris domains in Fig. 1 do not take stellar structure into account. In particular, the geodesic model treats all points in these domains equally, whereas in any physical star, the density profile is peaked at the centre and decays towards  $R_*$ . This difference becomes particularly important for  $L_{\rm cm}$  in the range  $L_{\rm cm} < L_{\rm cap} < L_{\rm cm} + (\Delta L)_{\rm max}$ . In the geodesic model, the CM will be captured in this range, but there will be uncaptured debris that may produce a self-intersection. However, in a physical star, this uncaptured debris will have low density since it arises from the stellar envelope, and will thus only weakly self-intersect.

To express the prompt self-intersection condition for the equatorial debris, let  $\psi(u, \tau)$  be the collection of equatorial debris geodesics,  $\psi : \mathbb{R}^2 \times \mathbb{R} \to \mathcal{M}$ , where  $u = (\tilde{X}^{(1)}, \tilde{X}^{(3)}) \in \mathbb{R}^2$  labels a geodesic in the collection by its (unscaled) spatial FNCs before disruption,  $\tau \in \mathbb{R}$  gives the proper time along a geodesic, and  $\mathcal{M}$  is the spacetime manifold. A self-intersection will occur if there exist two distinct points  $u_1$  and  $u_2$  and some times  $\tau_1$  and  $\tau_2$  such that  $(x^{\mu\circ}\psi)(u_1, \tau_1) = (x^{\mu\circ}\psi)(u_2, \tau_2)$ , where equivalence in the  $\phi$ -coordinate is defined such that the two expressions differ by at least  $2\pi$ .

However, this mathematical relation is cumbersome to implement numerically, so we instead adopt an approximate condition for selfintersection. If  $V(r_{-}(L_{max})) \leq E(L_{max})$ , then all of the debris will be captured. If  $V(r_{-}(L_{max})) > E(L_{max})$  and  $V(r_{-}(L_{min})) \leq E(L_{min})$ , then some (but not all) of the debris will be captured, and some of the uncaptured debris must promptly self-intersect. This is because the *EL* parameter space is smooth, so there will be geodesics with pericentres arbitrarily close to the event horizon that will rapidly precess and intersect the geodesics that have larger pericentres. If  $V(r_{-}(L_{min})) > E(L_{min})$ , then none of the debris will be captured. In this case, we select the debris elements with the smallest and largest values of *L*, which we label as  $\gamma(L_{min})$  and  $\gamma(L_{max})$ . These two have among the smallest and largest values of  $(r_p)_{GR}$ , and will



Figure 2. Orbit snapshots at a coordinate time *t* showing the self-intersection behaviour of the equatorial debris geodesics, for  $M/M_{\odot} = 5 \times 10^4$ , Solar-type stars,  $E_{\rm cm} = 1$ , and two different values of  $L_{\rm cm}$ . The black circle shows the Schwarzschild radius  $r_{\rm S} = 2M$ , the location of the event horizon. The red (blue) curve shows the geodesic with the smallest (largest) value of *L*. The grey curves show 100 geodesics with randomly selected values of *E* and *L*. (a)  $L_{\rm cm} = 4.1M$ . This falls in the regime  $V(r_{-}(L_{\rm max})) > E(L_{\rm max})$  and  $V(r_{-}(L_{\rm min})) \leq E(L_{\rm min})$ , in which some of the geodesics are captured and some of the uncaptured geodesics must promptly self-intersect. (b)  $L_{\rm cm} = 4.72M$ . This falls in the regime  $V(r_{-}(L_{\rm min})) > E(L_{\rm max}) > 2\pi$  for some *t*, so the debris promptly self-intersects.

be among the leading and trailing geodesics to reach the SMBH. We integrate these geodesics, and classify the outcome as a prompt self-intersection if there is a coordinate time *t* at which  $\Delta \phi \equiv \phi(L_{\min}) - \phi(L_{\max}) \geq 2\pi$ . If this condition is met, then there likely exist two geodesics that satisfy the exact condition above. We note that this approximate condition is neither necessary nor sufficient for the exact condition. If  $(x^{\mu \circ}\psi)(u_1, \tau_1) = (x^{\mu \circ}\psi)(u_2, \tau_2)$ , then it is possible that  $\Delta \phi < 2\pi$ since  $\gamma(L_{\min})$  and  $\gamma(L_{\max})$  are not rigorously the leading and trailing geodesics. If  $\Delta \phi \geq 2\pi$ , then it is possible that  $(x^{\mu \circ}\psi)(u_1, \tau_1) \neq (x^{\mu \circ}\psi)(u_2, \tau_2)$  because  $\gamma(L_{\min})$  fails to catch up to any of the other geodesics. These two possibilities, though, are unlikely. Fig. 2 shows the trajectories of geodesics for one set of SMBH and stellar parameters and two different values of  $L_{cm}$ , which produce prompt self-intersections in these two regimes.

Fig. 3 shows the range of  $\beta$  over which we expect prompt selfintersections as a function of the SMBH mass, for Solar-type stars. The minimum (maximum) penetration factor is  $\beta_{\min} \simeq 50$  ( $\beta_{\max} \simeq 560$ ) for  $M/M_{\odot} = 10^4$ , and decreases to  $\beta_{\min} \simeq 5.6$  ( $\beta_{\max} \simeq 6.2$ ) for  $M/M_{\odot} = 10^6$ . The event horizon sets the length-scale for a given black hole mass. The curves for  $\beta_{\min}$  and  $\beta_{\max}$  thus converge at higher masses, and the condition  $R_* \ll r_t$  breaks down at lower masses  $M/M_* \lesssim 10^4$ . Fig. 4 shows the same for stars with  $M_*/M_{\odot} = 10$ .

The four black curves in Figs 3 and 4 divide the space into five regimes of interest: (1) below  $\beta_{\min, \text{uncap}}$  (solid), there are no prompt self-intersections because  $L_{cm}$  is too large, which leads to a large  $r_p$  and thus to a relative precession angle  $\delta \phi < 2\pi$ ; (2) between  $\beta_{\min, \text{uncap}}$  (solid) and  $\beta_{\max, \text{uncap}}$  (dashed), none of the debris gets captured, and it precesses sufficiently to produce a self-intersection; (3) between  $\beta_{\max, \text{uncap}}$  (dashed) and  $\beta(L_{cm} = L_{cap})$  (dotted), some of the debris gets captured but the CM does not, and the remainder necessarily self-intersects; (4) between  $\beta(L_{cm} = L_{cap})$  (dotted) and  $\beta_{\max, cap}$  (dotted–dashed), some of the debris gets captured including

the CM, and the remainder necessarily self-intersects; and (5) above  $\beta_{\max, cap}$  (dotted–dashed), all of the debris gets captured.

Not all of the prompt self-intersections will lead to energetic collisions. The observationally significant self-intersections will occur in regimes (2) and (3), where the CM is not captured. The colliding debris has more mass and a higher density here relative to the other regimes, since the stellar density profile is peaked at the centre and decays towards  $R_*$ . It is these energetic collisions that will lead to qualitatively different behaviour and new emission signatures. In contrast, the events in regime (4) will produce weaker self-intersections.

The scaling of  $\beta_{\rm min}$  with  $M/M_*$  calculated here exhibits the opposite trend to that found in our order of magnitude, analytic estimate in equation (8). For  $M_* = 1 M_{\odot}$ , the two roughly agree for  $M/M_{\odot} \sim (0.6-1) \times 10^5$ ; for  $M_* = 10 M_{\odot}$ , they roughly agree for  $M/M_{\odot} \sim (2-4) \times 10^5$ . The analytic estimate is inaccurate for SMBH masses above and below this. For masses above this, though, the range of  $\beta$  for a self-intersection shrinks rapidly.

For comparison, Evans et al. (2015) examined deep encounters with  $\beta = 10$  and 15 of Solar-type stars incident on an SMBH of mass  $M = 10^5 M_{\odot}$ . These values of  $\beta$  lie below the range  $\beta \simeq 22-35$  that we find are required for prompt self-intersection. For these shallower encounters, though, the above authors still observe efficient debris circularization due to apsidal precession and the rapid formation of an accretion disc.

#### **3 HYDRODYNAMIC SIMULATIONS**

In this section, we perform hydrodynamic simulations of deep TDEs of Solar-type stars ( $M_* = 1 M_{\odot}$  and  $R_* = 1 R_{\odot}$ ) by SMBHs of masses  $M/M_{\odot} = (0.6, 1, 1.4) \times 10^5$  (selected from Fig. 3) to validate the range of  $\beta$  that will produce prompt self-intersections. We use the SPH code PHANTOM (Price et al. 2018), which has been



Figure 3. The range of  $\beta = L_t^2/L_{cm}^2$  over which the debris will promptly self-intersect (black curves). The solid (dashed) curve shows the minimum (maximum) value  $\beta_{min, uncap}$  ( $\beta_{max, uncap}$ ) for which there is a self-intersection and in which none of the debris is captured. The dotted curve shows the GR boundary for the star's CM to get captured by the BH,  $\beta(L_{cm} = L_{cap})$ . The dotted–dashed curve shows the value  $\beta_{max, cap}$  at which all of the debris gets captured. The blue, solid lines show the Newtonian boundaries for the star to absorb the BH,  $\beta(L_{cm}^2 = 2MR_*)$ , the star's CM to get captured by the BH,  $\beta(L_{cm}^2 = 2Mr_s)$ , and the star to avoid disruption,  $\beta(L_{cm} = L_t)$ . The red, dotted, vertical lines show the SMBH masses at which  $L_{cap}^2 = 2MR_*$  and  $R_* = r_S$ . The disrupted stars are Sun-like ( $M_*/M_{\odot} = 1$  and  $R_*/R_{\odot} = 1$ ). (a)  $\beta$  versus  $M/M_{\odot}$  for the range of BH masses for which our approximations hold. (b) The 'TDE triangle' (adapted from Luminet & Pichon 1989a). The grey, solid, vertical lines show the boundary of the mass range in panel (a).



Figure 4. The same as Fig. 3, but for stars with  $M_*/M_{\odot} = 10$  and a mass-radius relation of  $R_* = R_{\odot}(M_*/M_{\odot})^{\alpha}$  where  $\alpha = 0.57$ , which holds for main-sequence stars with masses  $M_*/M_{\odot} \gtrsim 1$  (Torres et al. 2010).

successfully used to study a range of TDE phenomena (Coughlin & Nixon 2015; Coughlin et al. 2016; Bonnerot et al. 2016; Golightly, Coughlin & Nixon 2019). In contrast to these previous studies, we primarily seek to model the orbit and tidal deformation of the debris, and do not seek to accurately model the strong compression, shock, and collision physics. Unlike the geodesic model, though, the simulations incorporate pressure and self-gravity, and the star can experience tidal distortions prior to reaching the tidal radius.

We model the gravity of the SMBH using the generalized Newtonian potential developed by Tejeda & Rosswog (2013), which accurately reproduces several features of the Schwarzschild metric. In particular, it captures the orbital frequencies with an error  $\lesssim 6$  per cent and exactly reproduces the apsidal precession angle for zero-energy orbits, making it well suited for studying TDEs. Bonnerot et al. (2016) successfully used this potential in PHANTOM

to examine debris circularization and accretion disc formation. We set the accretion radius of the SMBH to be 1 per cent larger than the Schwarzschild radius; the SPH particles that cross this radius are captured and removed from the simulation.

We model the star as a polytrope with  $\gamma = 5/3$  (Hansen, Kawaler & Trimble 2004). To generate the polytrope, we follow the procedure outlined in Coughlin & Nixon (2015), and place the SPH particles on a tightly packed sphere, stretch the sphere towards a polytropic distribution, and relax the configuration for 10 sound-crossing times to produce a static initial state, which closely matches the known analytical solution.

To simulate an encounter with a penetration factor  $\beta$ , we place the relaxed star on a Newtonian parabolic orbit at an initial distance  $r_i = 3r_t$  and with pericentre  $r_p = r_t/\beta$  (we also ran a few encounters with  $r_i = 5r_t$  and found only small differences).



Figure 5. The column density in the *xy*-plane of the disrupted debris near pericentre for Solar-type stars and different values of  $M/M_{\odot}$  and  $\beta$ . The *xy*-axes are in units of  $r_g = GM/c^2$ , and the column bar gives the column density on a logarithmic scale. The top row shows  $M/M_{\odot} = 0.6 \times 10^5$ , the middle row shows  $M/M_{\odot} = 10^5$ , and the bottom row shows  $M/M_{\odot} = 1.4 \times 10^5$ . From left to right, the columns show: (a), (e), (i) the debris does not self-intersect; (b), (f), (j) the debris self-intersects; (c), (g), (k) the CM of the star is captured and the remaining debris weakly self-intersects; and (d), (h), (l) most of the debris is captured.

This setup is equivalent to initializing the Newtonian orbit of the stellar CM with the same angular momentum as the corresponding GR orbit; the generalized Newtonian potential should then recover the correct GR orbit. We note, though, that there are several ways to identify a GR orbit with a Newtonian orbit (Servin & Kesden 2017).

We use  $\sim 10^6$  SPH particles for each simulation. We do not account for shock heating, which is essential for capturing the evolution of the debris after self-intersection. However, our goal here is to test for the existence of the self-intersection, prior to which shock heating should not be important in the midplane. The selfgravity of the SPH particles is implemented using a tree algorithm; we adopt an opening angle criterion of  $\theta = 0.5$  to adequately capture the short-range forces (Gafton & Rosswog 2011). We produce images of the encounters using the visualization tool SPLASH (Price 2007).

Fig. 5 shows the column density in the *xy*-plane of the disrupted debris near pericentre for Solar-type stars and different values of  $M/M_{\odot}$  and  $\beta$ . For  $M/M_{\odot} = (0.6, 1, 1.4) \times 10^5$ , the SPH simulations give  $\beta_{\min} \simeq 27$ , 22, and 19 for self-intersection. These values are in close agreement with those from the geodesic model ( $\beta_{\min} \simeq 28$ , 22, and 19; Fig. 3), with a slightly shallower scaling of  $\beta_{\min}$  with  $M/M_{\odot}$ . The SMBHs in the simulations begin capturing the stellar CM around  $\beta = 38$ , 28, and 22 and capture most of the debris by  $\beta = 44$ , 32, and 24, which are again in close agreement with

the values of  $\beta(L_{\rm cm} = L_{\rm cap})$  and the region between  $\beta(L_{\rm cm} = L_{\rm cap})$  and  $\beta_{\rm max}$  predicted by the geodesic model. The simulations also confirm that the higher mass SMBHs require a smaller range of  $\beta$  for self-intersection.

These simulations confirm the basic predictions of the geodesic model of Section 2.2 and the more crude, analytic estimates of Section 2.1. The initial tidal distortion of the star before it reaches the tidal radius could explain the slightly smaller values of  $\beta$  for low SMBH masses for which the SPH simulations yield self-intersections; the star is slightly elongated at the time it reaches  $r_t$ , so it does not need to be subsequently stretched by the amount predicted by the 'frozen-in' approximation in order to self-intersect. We note, however, that the minimum penetration factor for self-intersection that we find here ( $\beta_{\min} \simeq 22$  for  $M = 10^5 M_{\odot}$ ) is still well above the value of  $\beta = 10$  found numerically by Evans et al. (2015). The origin of this discrepancy is unclear, though it may be due to the softer polytropic equation of state that those authors employed.

#### **4 DISCUSSION**

In this paper, we examined a new regime of ultra-deep TDEs of main-sequence stars in which the disrupted debris promptly intersects itself at the first pericentre passage. This is in contrast to canonical TDEs in which the debris gradually intersects itself following the return of the debris to pericentre (Rees 1988). We calculated the range of SMBH masses M and penetration factors  $\beta$  for which these prompt self-intersections occur, using (1) a rough, order-of-magnitude, analytic estimate (Section 2.1); (2) a geodesic model under the impulse and 'frozen-in' approximations (Section 2.2); and (3) SPH simulations (Section 3). In all three of these approaches, we demonstrated that one needs a combination of large penetration factor ( $\beta \gtrsim 10$ ) and small black hole mass ( $M \lesssim 10^6 M_{\odot}$ ) in order for the debris to experience extreme tidal distortion as it plunges within the tidal sphere, to travel through large precession angles at pericentre ( $\gtrsim 2\pi$ ), and to avoid plunging into the SMBH.

These ultra-deep TDEs will produce observable electromagnetic (EM) and GW signals closely spaced in time. We provide rough estimates for the multimessenger signatures of such an event here, but leave a detailed analysis to a future study. We then briefly discuss the detection prospects for these events.

We begin with an estimate of the prompt radiation emitted in the self-intersection. We model the debris stream as a cylinder of length  $l \sim r_{\rm p}$  and radius  $r \sim R_{\rm *}$ . A smaller portion  $l_{\rm c}$  < l of the debris stream is shocked in the intersection. This is a strong shock, which deposits a thermal energy density of order  $\rho v_s^2$ , where  $\rho \sim 3M_*/4\pi R_*^3$  is the debris mass density (assumed constant) and  $v_s$  is the shock velocity, which roughly equals the debris velocity at pericentre,  $v_{\rm s} \sim v_{\rm p} \sim (GM/r_{\rm p})^{1/2}$ . The stream is optically thick, so only thermal energy in the surface layers can diffuse out before the remainder is degraded by adiabatic expansion. The optical depth of the surface layer is  $\tau = \rho \kappa \Delta R$ , where  $\Delta R$  is its thickness and  $\kappa \sim 0.4 \text{ cm}^2\text{g}^{-1}$  is the opacity, assumed to be dominated by electron scattering. If we impose the condition that the photon diffusion time through the layer,  $t_{\rm diff} \sim \tau \Delta R/c$ , must be shorter than the debris expansion time,  $t_{\rm exp} \sim R_*/v_{\rm p}$ , then we obtain  $\Delta R \lesssim (cR_*/\rho\kappa v_p)^{1/2}$ . The thermal energy in the surface layer is then  $\Delta E \sim (2\pi R_* l_c \Delta R)(\rho v_s^2) \sim 2\pi l_c (R_*^3 v_p^3 c \rho / \kappa)^{1/2}$ . For  $M \sim 10^5 \, M_{\odot}$ , Solar-type stars,  $r_{\rm p} \sim 5 r_{\rm g}$ , and an interaction length of  $l_c \sim R_*$ , this is  $\Delta E \sim 1.3 \times 10^{48}$  erg. The light crossing time,  $t_{\rm lc}$  $\sim R_*/c \sim 2.3$  s, is much larger than the photon diffusion time,  $t_{\rm diff} \sim$  $1.2 \times 10^{-5}$  s; the former thus determines the time-scale over which the energy will appear to be radiated to a distant observer, which gives an observed luminosity of order  $L \sim 5.5 \times 10^{47}$  erg s<sup>-1</sup>. The effective temperature T can also be estimated by  $L = (2\pi R_* l_c)\sigma T^4$ , giving  $T \sim 2.4 \times 10^7$  K ( $kT \sim 2.1$  keV, where k is the Boltzmann constant). The collision will thus produce a short, bright flare in X-ray wavelengths.

As discussed above, the strong shock from self-intersection converts much of the kinetic energy ( $\sim \rho v_{\rm p}^2$ ) into thermal energy, which is comparable to the gravitational binding energy. Following this, the fate of the debris is uncertain; some will plunge into the black hole, some will form a disc and accrete onto the black hole through viscous processes, and some will be ejected. The debris that plunges into the black hole will not emit an observable EM signature. The debris that accretes will have a prompt accretion phase over the initial viscous time-scale,  $t_{\rm visc}$ , and a delayed accretion phase over a longer time-scale. For the prompt phase, we can roughly estimate the viscous time  $t_{visc}$  using the  $\alpha$ -viscosity prescription for thin discs developed by Shakura & Sunyaev (1976), which gives  $t_{\rm visc} \sim \alpha^{-1} (h/r)^{-2} P$  where the debris has scale height h, radial extent r, orbital period P, and dimensionless viscous parameter  $\alpha$ , though we note that the accreting debris is well outside the thin disc regime. For  $h \sim R_*, r \sim r_p, P \sim 2\pi (r_p^3/GM)^{1/2}, \alpha \sim$ 0.1, and the stellar and black hole parameters above, we find  $t_{\rm visc}$  ~ 6.5 min. The accretion rate is then  $\dot{M} \sim \eta M_*/t_{\rm visc}$ , where  $\eta$  is the fraction of debris that is promptly accreted. For  $\eta \sim 0.1$ –0.5, this yields  $\dot{M} \sim (0.8-4) \times 10^4 \,\mathrm{M_{\odot}yr^{-1}}$ . Evans et al. (2015) found similar accretion rates and time-scales for the prompt accretion episodes in their simulations, though for shallower encounters than considered here. We can estimate the accretion luminosity as  $L \sim \epsilon \dot{M} c^2$  erg s<sup>-1</sup>, where  $\epsilon$  is the radiative efficiency. For even a modest  $\epsilon \sim 0.1$ , the emission is highly super-Eddington,  $L/L_{\rm Edd} \sim 10^7 - 10^8$ . The radiation may drive an outflow from the disc, yielding an observed luminosity that is Eddington-limited, or it may be highly beamed in the form of a jet that does not unbind the disc, yielding an intrinsic accretion rate close to  $\dot{M}$ (Coughlin & Begelman 2014). For the delayed phase, it is unclear whether the debris accretes with the characteristic  $t^{-5/3}$  decay of conventional TDEs (Kawana et al. 2018; Anninos et al. 2018), or at a roughly constant rate (Evans et al. 2015), or exhibits an altogether different behaviour. The debris that is ejected, both from the self-intersection and the super-Eddington accretion, can produce an afterglow when it collides with matter surrounding the galactic nucleus.

There is another potential EM signature that may occur in a deep encounter even before the initial pericentre passage. A star approaching a SMBH in a deep encounter may experience strong tidal compression as it approaches pericentre, which will generate a shock wave that propagates to the surface, heats the outer layers, and produces an X-ray signature (Kobayashi et al. 2004; Guillochon et al. 2009; Yalinewich et al. 2019). If compression does occur, it may ignite nuclear reactions (Carter & Luminet 1982; Bicknell & Gingold 1983). Early studies of the X-ray breakout examined encounters with black hole masses  $M \sim 10^6 M_{\odot}$ , Solartype stars, and  $\beta \sim 5$ –10, and found luminosities  $L \sim 10^{42}$ – $10^{44}$ erg s<sup>-1</sup> at average photon energies  $E \sim 1-4$  keV (Kobayashi et al. 2004; Guillochon et al. 2009). Recently, Yalinewich et al. (2019) lowered this prediction to  $L \sim 10^{41} \text{ erg s}^{-1}$  at  $E \sim 1\text{--}10$  keV, the reduction arising from a more rapid drop in the shock velocity with increasing distance (decreasing density) from the midplane. For ultra-deep encounters, the debris may even spread sufficiently before pericentre to prevent X-ray breakout altogether (Evans et al. 2015).

It is interesting to compare the two types of X-ray flares discussed above: one from self-intersection in ultra-deep encounters, and one from tidal compression in general deep encounters. The selfintersection flare is ~3 orders of magnitude brighter than the compression flare. The higher brightness arises because the specific kinetic energy budget available for shock heating is much larger for self-intersection,  $v_p^2 \sim GM/r_p$ , than tidal compression,  $v^2 \simeq \beta^2(GM_*/R_*)$  (Carter & Luminet 1982). Even if the self-intersection shock degrades by ~2–3 orders of magnitude like the compression shock, it will still produce an X-ray flare at least as bright as the most optimistic estimates from the compression shock.

Deep encounters will also produce two types of GW signatures. The first signature arises from the orbital motion of the debris near pericentre (Kobayashi et al. 2004; Guillochon et al. 2009), including when the debris is fully captured (East 2014). The GW frequency and strain for these events are roughly (Kobayashi et al. 2004; Guillochon et al., 2009)

$$f \sim \left(\frac{GM}{r_{\rm p}^3}\right)^{1/2} \sim (6.3 \times 10^{-4} \,{\rm Hz})\beta^{3/2} m_*^{1/2} r_*^{-3/2}$$
 (25)

$$h \sim \frac{GM_*r_{\rm S}}{c^2 dr_{\rm p}} \sim 4.4 \times 10^{-23} \beta d_{10}^{-1} m_*^{4/3} r_*^{-1} M_5^{2/3} \tag{26}$$

where  $d_{10} \equiv d/(10 \text{ Mpc})$  with d being the distance to the event. For the distance  $d_{10} = 1$  and the parameters in Fig. 3 (i.e. the stellar parameters, the range of SMBH masses, and the values of  $\beta_{min}$ ), we find  $f \sim (2.2-0.06) \times 10^{-1}$  Hz and  $h \sim (0.47-1.1) \times 10^{-21}$ . These lie outside the sensitivity of both the Advanced Laser Interferometer Gravitational-Wave Observatory (LIGO, LIGO Scientific Collaboration et al. 2015) and the Laser Interferometer Space Antenna (LISA, Amaro-Seoane et al. 2017), but are accessible to currently proposed GW detectors (Moore, Cole & Berry 2015), notably those in the decihertz range (Kawamura et al. 2006; Sato et al. 2017). For the parameters in Fig. 4, we find  $f \sim (4.7-0.17) \times 10^{-2}$  Hz and  $h \sim$  $(0.49-1.1) \times 10^{-20}$ . These fall marginally within the sensitivity of LISA. The second GW signature arises from the tidal deformation of the star itself (Guillochon et al. 2009; Stone et al. 2013). For our parameter range, the frequency and strain are roughly (Stone et al. 2013)

$$f \sim (3.8 \times 10^{-5} \text{ Hz}) \beta^4 m_*^{1/2} r_*^{-3/2}$$
 (27)

$$h_{+} \sim 1.2 \times 10^{-24} \beta^{-2} d_{10}^{-1} m_{*}^{11/6} r_{*}^{-1} M_{5}^{1/3}$$
(28)

These signals are not detectable by advanced LIGO or LISA, and fall only marginally within the sensitivity of future GW detectors.

Ultra-deep TDEs are statistically rare due to the large penetration factors required to achieve them. The probability of a prompt selfintersection depends on the BH mass function over our mass range and the state of the stellar loss cone at a given BH mass, namely the degree to which it is 'full' ('pinhole' regime) or 'empty' ('diffusive' regime) (Frank & Rees 1976; Lightman & Shapiro 1977). We assume a uniform distribution for the BH mass function over our mass range, though we note that the scaling depends on the model assumptions used to construct it (Stone & Metzger 2016; Kochanek 2016; van Velzen 2018). The TDE rate is then  $\dot{N}_{\text{TDE}} \sim 10^{-5}$ Mpc<sup>-3</sup> yr<sup>-1</sup> for SMBHs with masses  $M \sim (10^4 - 10^6) M_{\odot}$  (Stone & Metzger 2016). We also assume that the loss cone is 'full' over our mass range, which likely holds for SMBHs with masses  $M \sim (10^5 - 10^6) M_{\odot}$  (Stone & Metzger 2016). The incident stars will then have penetration factors distributed according to the probability density function (PDF)  $f_{\rm B}(\beta) = \beta^{-2}$  (Luminet & Barbuy 1990; Stone & Metzger 2016; Kochanek 2016). The probability of a significant prompt self-intersection over our mass range is then simply  $P_{\rm SI} \simeq \beta_{\rm min}^{-1} - \beta (L_{\rm cm} = L_{\rm cap})^{-1} \lesssim 1$  per cent, yielding an ultra-deep TDE rate of  $\dot{N}_{\rm UD} \lesssim 10^{-7}$  Mpc<sup>-3</sup> yr<sup>-1</sup>.

The X-ray flare from self-intersection evolves quickly, akin to a gamma-ray burst (GRB), and distinguishes ultra-deep TDEs from conventional ones. We estimate its detectability. We use the current parameters for a flat  $\Lambda$  cold dark matter cosmology (Hinshaw et al. 2013). For simplicity, we round the numbers in our emission estimate above, and consider a monochromatic source with emitted luminosity  $L_{\rm e} \sim 5 \times 10^{47}$  erg s<sup>-1</sup>, energy  $E_{\rm e} \sim 2$  keV (frequency  $v_e = E_e/h$ , where *h* here is the Planck constant), and duration  $\Delta t_{\rm e} \sim 2$  s. If the source is at redshift z, the detector will observe the event with energy  $E_0 = E_e/(1 + z)$  (frequency  $v_0 =$  $v_e/(1 + z)$ ) over a duration  $\Delta t_o = (1 + z)\Delta t_e$ . The flux at the detector is  $S_0 = L_e/4\pi D_L^2$ , where  $D_L$  is the luminosity distance. We take the integration time at the detector to be  $\Delta t_{int} \sim \Delta t_e$ . The number of counts measured at the detector is then  $n = S_0 \Delta t_{int} A/E_0$ , where A is the effective area of the detector. The background is low since our integration time is short, so a signal of n =10 counts provides a  $\sim 3\sigma$  detection. The maximum luminosity distance  $D_{\rm I}$  that can be observed at this level is given by  $D_{\rm I}/(1 +$ z)<sup>1/2</sup> =  $(L_e \Delta t_{int} A/4\pi n E_e)^{1/2}$ , which yields a corresponding comoving volume  $V_{\rm C}$ . The event rate within this volume is  $R = \dot{N}_{\rm UD} V_{\rm C}$ . For detectors with a narrow field of view  $\Omega$ , the detection rate is then  $R_{\rm det} = R\Omega/4\pi$ .

We estimate the detection rate using parameters characteristic of two X-ray missions with the required energy range and narrow fields of view: the Swift X-ray Telescope (XRT, Burrows et al. 2005), and the upcoming extended Roentgen Survey with an Imaging Telescope Array (eROSITA, Merloni et al. 2012). The X-ray flare is below the energy range of the Swift Burst Alert Telescope (BAT, Krimm et al. 2013). For *Swift* XRT ( $A \sim 125 \text{ cm}^2$ , and  $\Omega = 23.6$ arcmin<sup>2</sup>), we find a limiting distance  $D_{\rm L} \sim 9$  Gpc with  $E_{\rm o} \sim 0.9$  keV,  $\Delta t_{\rm o} \sim 4$  s,  $R \sim 2 \times 10^4$  yr<sup>-1</sup>, and  $R_{\rm det} \sim 0.1$  yr<sup>-1</sup>, which makes a serendipitous detection unlikely. For eROSITA ( $A \sim 1000 \text{ cm}^2$ , and  $\Omega = 0.833 \text{ deg}^2$ ), we find  $D_{\rm L} \sim 36$  Gpc with  $E_{\rm o} \sim 0.4$  keV,  $\Delta t_{\rm o} \sim$ 10 s,  $R \sim 2 \times 10^5$  yr<sup>-1</sup>, and  $R_{det} \sim 3$  yr<sup>-1</sup>, which is slightly more promising. A higher detection rate can be achieved using an allsky monitor with the appropriate energy range and time resolution, such as the Monitor of All-sky X-ray Image Solid-State Slit Camera (Matsuoka et al. 2009; Tomida et al. 2011).

Recently, several groups have discovered X-ray transients with the *Chandra X-ray Observatory* that exhibit a prompt, high luminosity precursor flash followed by a longer term, power-law decay (Jonker et al. 2013; Glennie et al. 2015; Bauer et al. 2017). The above authors suggest several possible progenitors, including the tidal disruption of a WD and an off-axis short GRB. To these, we can add ultra-deep disruptions of main-sequence stars, which our predictions suggest have similar behaviour, time-scales, energies, and luminosities. The above authors also estimate similar all-sky event rates as ours, one finding  $\sim 10^{-7}$  Mpc<sup>-3</sup> yr<sup>-1</sup> at  $z \sim 1$  (Bauer et al. 2017), and another finding  $\sim 1.4 \times 10^5$  yr<sup>-1</sup> for *Chandra* (Glennie et al. 2015), though these have large uncertainties.

In addition, the potential late-time dynamics may be observable in wide-field optical surveys. Though  $\dot{N}_{\rm UD}$  is small, current wide-field surveys such as the Zwicky Transient Facility (Bellm et al. 2019) and upcoming surveys like the Large Synoptic Survey Telescope (Ivezić et al. 2019) should collectively detect hundreds to thousands of TDEs, yielding a few to dozens of these rare events.

# ACKNOWLEDGEMENTS

We thank the anonymous referee for providing thorough comments. We thank Eliot Quataert, Jeremy Hare, and Alex Krolewski for helpful discussions, and Peter Jonker for notifying us of the recent X-ray observations. This research used resources of the National Energy Research Scientific Computing Center, a Department of Energy Office of Science User Facility supported by the Office of Science of the U.S. Department of Energy under contract no. DE-AC02-05CH11231. This work was supported by the National Science Foundation under grant no. 1616754. ERC was supported by the National Aeronautics and Space Administration through the Einstein Fellowship Program, grant PF6-170170. CJN is supported by the Science and Technology Facilities Council (grant no. ST/M005917/1).

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# APPENDIX A: ORTHONORMAL TETRAD

In Section 2.2, we modelled the debris elements as independent geodesics in the Schwarzschild metric, and used an ONT  $\lambda_{(\mu)}$  that is parallel propagated along the time-like, CM geodesic to define FNCs. In this appendix, we give the components of the tetrad elements in the Schwarzschild coordinate basis; these were presented in earlier work (Luminet & Marck 1985; Brassart & Luminet 2010), and obtained from the more general expressions derived by Marck (1983) in the Kerr metric.

The zeroth element of the tetrad is simply the four velocity of the CM of the star,  $\lambda_{(0)} = u_{cm} = \dot{t}\partial_t + \dot{r}\partial_r + \dot{\phi}\partial_{\phi}$ . We considered the CM geodesic to move in the equatorial plane ( $\theta = \pi/2$ ,  $\dot{\theta} = 0$ ) without loss of generality, so the second element is simply  $\lambda_{(2)} = \frac{1}{r}\partial_{\theta}$ . The first element is

$$\lambda_{(1)}^{t} = (r\dot{r}\cos\psi - EL\sin\psi)\left(1 - \frac{2M}{r}\right)^{-1}(r^{2} + L^{2})^{-1/2} \quad (A1)$$

$$\lambda_{(1)}^{r} = (Er\cos\psi - \dot{r}L\sin\psi)(r^{2} + L^{2})^{-1/2}$$
(A2)

$$\lambda^{\theta}_{(1)} = 0$$

(A3)

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$$\lambda^{\phi}_{(1)} = -\frac{(r^2 + L^2)^{1/2}}{r^2} \sin\psi$$
(A4)

The third element is

$$\lambda_{(3)}^{t} = (r\dot{r}\sin\psi + EL\cos\psi)\left(1 - \frac{2M}{r}\right)^{-1}(r^{2} + L^{2})^{-1/2} \quad (A5)$$

$$\lambda_{(3)}^r = (Er\sin\psi + \dot{r}L\cos\psi)(r^2 + L^2)^{-1/2}$$
(A6)

$$\lambda^{\theta}_{(3)} = 0 \tag{A7}$$

$$\lambda_{(3)}^{\phi} = \frac{(r^2 + L^2)^{1/2}}{r^2} \cos \psi \tag{A8}$$

The angle  $\psi$  is calculated from

$$\dot{\psi} = \frac{EL}{r^2 + L^2} \tag{A9}$$

We take  $\psi = 0$  at  $r = r_t$ , since we chose the point of disruption to be the reference point for our FNCs. This simplifies the above expressions at the tidal radius; in particular,  $\lambda_{(1)}^{\phi}$  vanishes.

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